

Hyperbolic models for diffusion equations

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Diffusion equations

- Many phenomena in nature are described by diffusion-type equations
- ① Fick's second law for particle concentration

$$\frac{\partial \varphi}{\partial t} = \operatorname{div} (D \nabla \varphi)$$

- ② Fourier's law for heat conduction leads to

$$\frac{\partial T}{\partial t} = \operatorname{div} (K \nabla T)$$

- ③ etc ...

Very "simple" structure, compares well with experimental observations.

Objective

We would like to provide first-order hyperbolic alternatives to the following systems

- 1 Euler equations supplemented by Fourier heat conduction

$$\frac{\partial \rho}{\partial t} + \operatorname{div}(\rho \mathbf{u}) = 0, \quad (1a)$$

$$\frac{\partial \rho \mathbf{u}}{\partial t} + \operatorname{div}(\rho \mathbf{u} \otimes \mathbf{u} + p(\rho, \eta) \mathbf{I}) = 0, \quad (1b)$$

$$\frac{\partial E}{\partial t} + \operatorname{div}(E \mathbf{u} + p(\rho, \eta) \mathbf{u} - K \nabla \theta(\rho, \eta)) = 0. \quad (1c)$$

- 2 Cahn-Hilliard equations

$$\frac{\partial c}{\partial t} = \Delta (c^3 - c - \gamma \Delta c). \quad (2)$$

Why are we doing this?

- 1 Restore the principle of causality :
information must not travel faster than light speed in vacuum.
(Trivially violated by Laplace operator)
- 2 Symmetric hyperbolic equations are well-posed.
- 3 Obtain an alternative description of known phenomena.
- 4 Chance it provides much easier/faster numerical simulations.

Plan of presentation

- 1 A hyperbolic model for heat conduction in compressible flows
 - Model Derivation
 - Hyperbolicity
 - Numerical results
- 2 A hyperbolic model for Cahn-Hilliard equations
 - Hyperbolicization approach
 - Numerical scheme
 - Results
- 3 Conclusion and Perspectives

Objective properties

We want to obtain a model that satisfies the following properties

- 1 First-order hyperbolic system
- 2 Can be cast into a Friedrichs symmetric form
- 3 Total Energy is conserved
- 4 Compatible with the second law of thermodynamics
- 5 Gallilean invariant
- 6 can be derived from a variational principle

About Euler-Lagrange equations

Given a Lagrangian, you can derive the Euler-Lagrange equation

$$\mathcal{L}(q, \dot{q}, \nabla q) \implies \frac{d}{dt} \left(\frac{\partial \mathcal{L}}{\partial \dot{q}} \right) + \operatorname{div} \left(\frac{\partial \mathcal{L}}{\partial \nabla q} \right) = \frac{\partial \mathcal{L}}{\partial q}$$

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Things are already more complicated for Euler equations

$$\mathcal{L}(\rho, \mathbf{u}) = \int_{\Omega_t} \left(\frac{1}{2} \rho \|\mathbf{u}\|^2 - \rho \varepsilon(\rho, \eta) \right) d\Omega,$$

$$\delta \rho = -\operatorname{div}(\rho \delta \mathbf{x}), \quad \delta \mathbf{u} = \frac{\partial \delta \mathbf{x}}{\partial t} + \frac{\partial \delta \mathbf{x}}{\partial \mathbf{x}} \mathbf{u} - \frac{\partial \mathbf{u}}{\partial \mathbf{x}} \delta \mathbf{x}$$

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After a bit of calculus $\implies \frac{\partial \rho \mathbf{u}}{\partial t} + \operatorname{div} \left(\rho \mathbf{u} \otimes \mathbf{u} + \rho^2 \frac{\partial \varepsilon}{\partial \rho} \mathbf{I} \right) = 0$

Euler equations for compressible fluids

$$\frac{\partial \rho}{\partial t} + \operatorname{div}(\rho \mathbf{u}) = 0, \quad (\text{mass})$$

$$\frac{\partial \rho \mathbf{u}}{\partial t} + \operatorname{div}(\rho \mathbf{u} \otimes \mathbf{u} + p(\rho, \eta) \mathbf{I}) = 0, \quad (\text{momentum})$$

$$\frac{\partial \rho \eta}{\partial t} + \operatorname{div}(\rho \eta \mathbf{u}) = 0. \quad (\text{entropy})$$

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Summing up these equations yields the energy conservation equation

$$\frac{\partial E}{\partial t} + \operatorname{div}(E \mathbf{u} + p(\rho, \eta) \mathbf{u}) = 0. \quad (\text{Energy})$$

Thermal displacement (Green-Naghdi 1991)

In this paper :

[1] Green, A. E., & Naghdi, P. (1991). A re-examination of the basic postulates of thermomechanics. Proceedings of the Royal Society of London. Series A: Mathematical and Physical Sciences, 432(1885), 171-194.

The authors introduce an independent auxiliary potential $\phi(\mathbf{x}, t)$ as a thermal analogue of the kinematic variables such that

$$\dot{\phi}(\mathbf{x}, t) = -\theta(\mathbf{x}, t)$$

One can then write the Lagrangian

$$\mathcal{L}(\rho, \mathbf{u}, \dot{\phi}) = \int_{\Omega} \left(\frac{1}{2} \rho \|\mathbf{u}\|^2 - \rho \varepsilon^*(\rho, \dot{\phi}) \right) d\Omega,$$

where

$$\varepsilon(\rho, \eta) = \varepsilon^*(\rho, \dot{\phi}) - \eta \dot{\phi}, \quad \text{with} \quad \eta = \frac{\partial \varepsilon^*}{\partial \dot{\phi}}.$$

Entropy as an Euler-Lagrange equation

Given the Lagrangian

$$\mathcal{L}(\rho, \mathbf{u}, \dot{\phi}) = \int_{\Omega} \left(\frac{1}{2} \rho \|\mathbf{u}\|^2 - \rho \varepsilon^*(\rho, \dot{\phi}) \right) d\Omega, \quad \left(\dot{\phi} = \frac{\partial \phi}{\partial t} + \mathbf{u} \cdot \nabla \phi \right)$$

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One obtains

$$\frac{\partial \rho \mathbf{u}}{\partial t} + \operatorname{div} \left(\rho \mathbf{u} \otimes \mathbf{u} + \rho^2 \frac{\partial \varepsilon^*}{\partial \rho} \mathbf{I} \right) = 0, \quad (\text{Euler-Lagrange for } \delta \mathbf{x})$$

$$\frac{\partial}{\partial t} \left(\rho \frac{\partial \varepsilon^*}{\partial \dot{\phi}} \right) + \operatorname{div} \left(\rho \frac{\partial \varepsilon^*}{\partial \dot{\phi}} \mathbf{u} \right) = 0, \quad (\text{Euler-Lagrange for } \delta \phi)$$

Entropy as an Euler-Lagrange equation

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One obtains

$$\frac{\partial \rho \mathbf{u}}{\partial t} + \operatorname{div} \left(\rho \mathbf{u} \otimes \mathbf{u} + \rho^2 \frac{\partial \varepsilon^*}{\partial \rho} \mathbf{I} \right) = 0, \quad (\text{Euler-Lagrange for } \delta \mathbf{x})$$

$$\frac{\partial}{\partial t} (\rho \eta) + \operatorname{div} (\rho \eta \mathbf{u}) = 0, \quad (\text{Euler-Lagrange for } \delta \phi)$$

$$\frac{\partial \rho}{\partial t} + \operatorname{div} (\rho \mathbf{u}) = 0 \quad (\text{Constraint})$$

- A similar idea was also used in Lagrangian coordinates in *Peshkov et.al. (2018)*.

Extension of Green-Naghdi's philosophy

Consider the Lagrangian

$$\mathcal{L}(\rho, \mathbf{u}, \nabla\phi, \dot{\phi}) = \int_{\Omega} \left(\frac{1}{2}\rho \|\mathbf{u}\|^2 - \rho\varepsilon^*(\rho, \dot{\phi}) - \frac{1}{2}\alpha(\rho) \|\nabla\phi\|^2 \right) d\Omega,$$

where the function $\alpha(\rho)$ is an arbitrary positive function of density.

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$$\frac{\partial\rho\mathbf{u}}{\partial t} + \operatorname{div}(\rho\mathbf{u} \otimes \mathbf{u} + P(\rho, \nabla\phi) \mathbf{I} + \alpha(\rho) \nabla\phi \otimes \nabla\phi) = 0,$$

$$\frac{\partial\rho\eta}{\partial t} + \operatorname{div}(\rho\eta\mathbf{u} + \alpha(\rho)\nabla\phi) = 0,$$

$$\text{where } P(\rho, \nabla\phi) = \rho^2 \frac{\partial\varepsilon^*}{\partial\rho} + \frac{1}{2}(\rho\alpha'(\rho) - \alpha(\rho)) \|\nabla\phi\|^2$$

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- Problem : PDE is of second order and depends on $\nabla\phi$.

Solution: First-order reduction

Recall that

$$\frac{\partial \phi}{\partial t} + \mathbf{u} \cdot \nabla \phi = -\theta(\rho, \eta)$$

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$$\nabla \left(\frac{\partial \phi}{\partial t} \right) + \nabla(\mathbf{u} \cdot \nabla \phi) = -\nabla(\theta(\rho, \eta))$$

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Recall that

$$\nabla \left(\frac{\partial \phi}{\partial t} \right) + \nabla (\mathbf{u} \cdot \nabla \phi) = -\nabla (\theta(\rho, \eta))$$

$$\frac{\partial \nabla \phi}{\partial t} + \nabla (\mathbf{u} \cdot \nabla \phi + \theta(\rho, \eta)) = 0$$

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$$\frac{\partial \nabla \phi}{\partial t} + \nabla (\mathbf{u} \cdot \nabla \phi + \theta(\rho, \eta)) = 0$$

Let us introduce $\mathbf{j} = \nabla \phi$ as an independent variable. Then \mathbf{j} satisfies

$$\frac{\partial \mathbf{j}}{\partial t} + \nabla (\mathbf{u} \cdot \mathbf{j} + \theta(\rho, \eta)) = 0$$

Dissipationless system of equations

$$\frac{\partial \rho}{\partial t} + \operatorname{div}(\rho \mathbf{u}) = 0,$$

$$\frac{\partial \rho \mathbf{u}}{\partial t} + \operatorname{div}(\rho \mathbf{u} \otimes \mathbf{u} + \Pi) = 0, \quad \Pi = P(\rho, \eta, \mathbf{j}) \mathbf{I} + \alpha(\rho) \mathbf{j} \otimes \mathbf{j}$$

$$\frac{\partial \mathbf{j}}{\partial t} + \nabla(\mathbf{j} \cdot \mathbf{u} + \theta(\rho, \eta)) + \left(\frac{\partial \mathbf{j}}{\partial \mathbf{x}} - \left(\frac{\partial \mathbf{j}}{\partial \mathbf{x}} \right)^T \right) \mathbf{u} = 0,$$

$$\frac{\partial \rho \eta}{\partial t} + \operatorname{div}(\rho \eta \mathbf{u} + \alpha(\rho) \mathbf{j}) = 0.$$

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Total energy conservation is obtained as a consequence

$$\frac{\partial E}{\partial t} + \operatorname{div}(E \mathbf{u} + \Pi \mathbf{u} + \mathbf{q}) = 0, \quad \mathbf{q} = \alpha(\rho) \theta(\rho, \eta) \mathbf{j}$$

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Additional term in the energy conservation is heat flux.

Rayleigh dissipation function

$$\frac{\partial \rho}{\partial t} + \operatorname{div}(\rho \mathbf{u}) = 0,$$

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$$\frac{\partial \mathbf{j}}{\partial t} + \nabla(\mathbf{j} \cdot \mathbf{u} + \theta(\rho, \eta)) + \left(\frac{\partial \mathbf{j}}{\partial \mathbf{x}} - \left(\frac{\partial \mathbf{j}}{\partial \mathbf{x}} \right)^T \right) \mathbf{u} = - \frac{\partial \mathcal{R}}{\partial \mathbf{j}},$$

$$\frac{\partial \rho \eta}{\partial t} + \operatorname{div}(\rho \eta \mathbf{u} + \alpha(\rho) \mathbf{j}) = \frac{\alpha(\rho)}{\theta(\rho, \eta)} \frac{\partial \mathcal{R}}{\partial \mathbf{j}} \cdot \mathbf{j}.$$

Here \mathcal{R} is the *Rayleigh dissipation* function and which we take in the simplest form as

$$\mathcal{R} = \frac{1}{2\tau} \|\mathbf{j}\|^2, \quad \frac{\partial \mathcal{R}}{\partial \mathbf{j}} = \frac{1}{\tau} \mathbf{j}$$

Energy convexity

Total energy is given by

$$E(\rho, \mathbf{m}, s, \mathbf{j}) = \frac{1}{2\rho} \|\mathbf{m}\|^2 + \rho\varepsilon(\rho, s/\rho) + \frac{1}{2}\alpha(\rho) \|\mathbf{j}\|^2, \quad \mathbf{m} = \rho\mathbf{u}, s = \rho\eta$$

Sufficient criterion for energy convexity

$$\text{if } \frac{\partial^2}{\partial \rho^2} \left(\frac{1}{\alpha(\rho)} \right) \leq 0, \quad \text{for } \rho > 0.$$

then E is also a convex function of \mathbf{Q} .

We choose a simple function fitting this criterion

$$\alpha(\rho) = \frac{\varkappa}{\rho}, \quad \varkappa = \text{cst.}$$

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$$\alpha(\rho) = \frac{\varkappa}{\rho}, \quad \varkappa = \text{cst.}$$

(Another possibility is $\alpha(\rho) = \text{cst}$, taken in *Peshkov et.al. (2018)*)

Hyperbolicity

system can be cast into quasilinear form

$$\frac{\partial \mathbf{V}}{\partial t} + \mathbf{A}(\mathbf{V}) \frac{\partial \mathbf{V}}{\partial \mathbf{x}} = 0$$

where \mathbf{A} admits 8 eigenvalues whose expressions are given by

$$\left\{ \begin{array}{l} \chi_1 = u_1 - \sqrt{Z_1 + Z_2}, \\ \chi_2 = u_1 - \sqrt{Z_1 - Z_2}, \\ \chi_{3-6} = u_1, \\ \chi_7 = u_1 + \sqrt{Z_1 - Z_2}, \\ \chi_8 = u_1 + \sqrt{Z_1 + Z_2} \end{array} \right. \quad \text{where} \quad \left\{ \begin{array}{l} Z_1 = \frac{1}{2} (a_p^2 + a_T^2 + a_j^2), \\ Z_2 = \sqrt{a_{pT}^4 + \frac{1}{4} (a_p^2 - a_T^2)^2}, \\ a_p^2 = \frac{\partial p}{\partial \rho}, \quad a_T^2 = \frac{\varkappa^2}{\rho^2} \frac{\partial \theta}{\partial \eta}, \\ a_{pT}^4 = \frac{\varkappa^2}{\rho^2} \frac{\partial p}{\partial \eta} \frac{\partial \theta}{\partial \rho}, \quad a_j^2 = \frac{2\varkappa^2}{\rho^2} (j_2^2 + j_3^2). \end{array} \right.$$

1D-study: Eigenfields

In one dimension of space, we can write the system as

$$\begin{aligned} \frac{\partial \rho}{\partial t} + u \frac{\partial \rho}{\partial x} + \rho \frac{\partial u}{\partial x} &= 0, \\ \frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + \frac{1}{\rho} \frac{\partial p}{\partial \rho} \frac{\partial \rho}{\partial x} + \frac{1}{\rho} \frac{\partial p}{\partial \eta} \frac{\partial \eta}{\partial x} &= 0, \\ \frac{\partial \eta}{\partial t} + u \frac{\partial \eta}{\partial x} + \frac{\varkappa^2}{\rho^2} \frac{\partial j}{\partial x} - \frac{\varkappa^2}{\rho^3} j \frac{\partial \rho}{\partial x} &= 0, \\ \frac{\partial j}{\partial t} + j \frac{\partial u}{\partial x} + u \frac{\partial j}{\partial x} + \frac{\partial \theta}{\partial \rho} \frac{\partial \rho}{\partial x} + \frac{\partial \theta}{\partial \eta} \frac{\partial \eta}{\partial x} &= 0. \end{aligned}$$

The eigenvalues are given by

$$\begin{cases} \lambda_1 = u - \sqrt{Y_1 + Y_2}, \\ \lambda_2 = u - \sqrt{Y_1 - Y_2}, \\ \lambda_3 = u + \sqrt{Y_1 - Y_2}, \\ \lambda_4 = u + \sqrt{Y_1 + Y_2}, \end{cases} \quad \text{where} \quad \begin{cases} Y_1 = \frac{1}{2} (a_p^2 + a_T^2), \\ Y_2 = \sqrt{a_{pT}^4 + Y_3^2}, \\ Y_3 = \frac{1}{2} (a_p^2 - a_T^2). \end{cases}$$

1D-study: Eigenfields

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Nature of the eigenfields (polytropic gas equation of state):

- System admits full basis of eigenvectors.

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Nature of the eigenfields (polytropic gas equation of state):

- System admits full basis of eigenvectors.
- Eigenfields associated to $\lambda_{1,4}$ are genuinely non-linear.

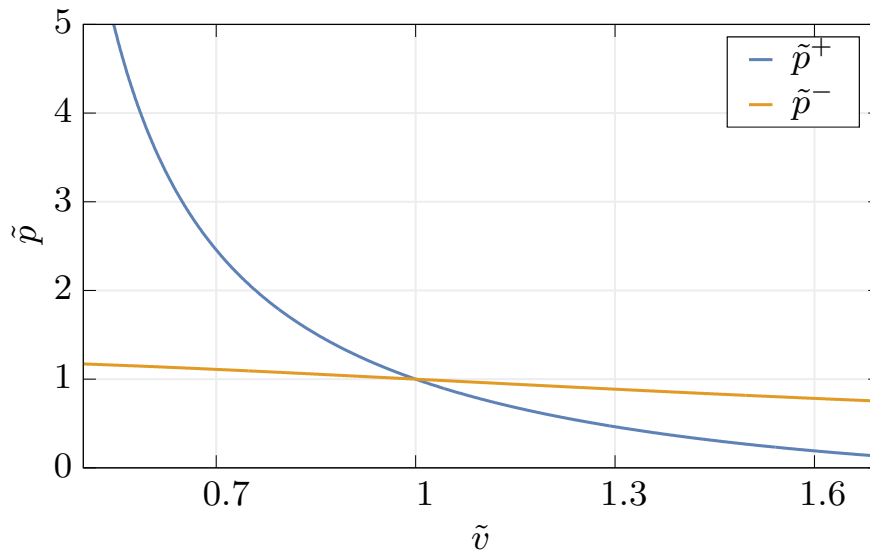
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Nature of the eigenfields (polytropic gas equation of state):

- System admits full basis of eigenvectors.
- Eigenfields associated to $\lambda_{1,4}$ are genuinely non-linear.
- Eigenfields associated to $\lambda_{2,3}$ are neither genuinely non-linear, neither linearly degenerate.

Hugoniot Locus (polytropic gas equation of state)



Study of the Hugoniot curves shows interesting possible solutions:

- Expansion shocks,
- Compression fans,
- Compound shocks.

Compound shocks

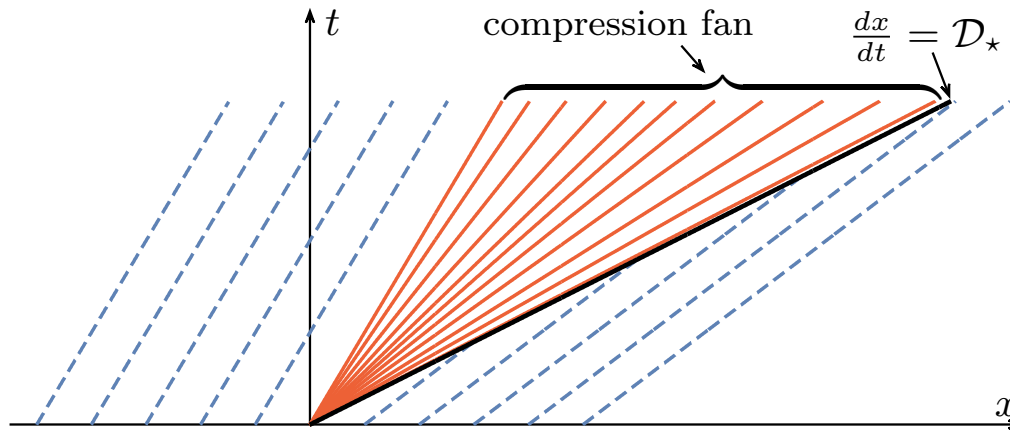


Figure 1: Schematic representation of the wave pattern in the $x - t$ plane, for a compound shock splitting solution. The shock propagates to the right, followed by a right facing compression fan.

Recovery of Fourier law: Shock tube problem

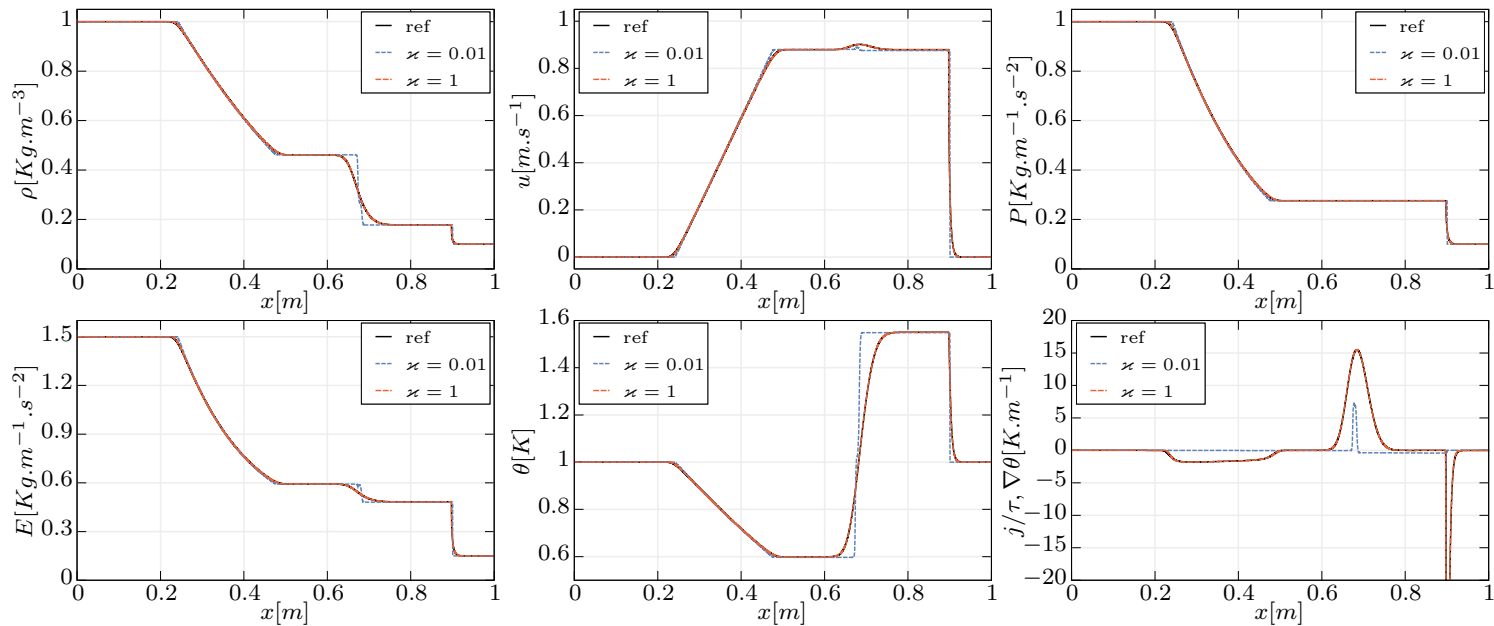


Figure 2: Shock tube with heat conduction. The solution is given at final time $t = 0.2$. Parameters: $CFL = 0.9$, $\gamma = 5/3$, $c_V = 3/2$, $K = 10^{-3}$. Relaxation time is taken as $\tau = \frac{K}{\alpha(\rho_0)\theta(\rho_0, \eta_0)}$

Expansion shock solution

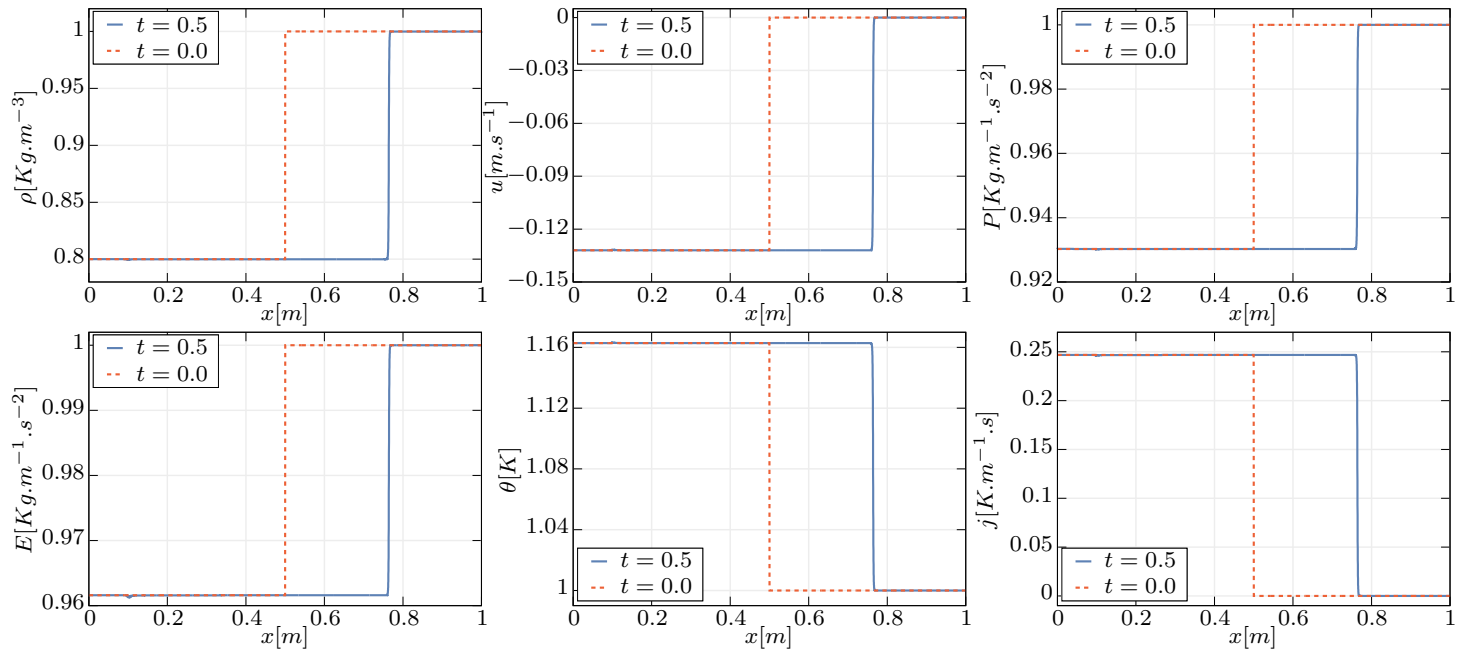


Figure 3: Numerical result for an expansion shock solution on the computational domain $[0, 1]$, discretized over $N = 10000$ cells displayed at final time $t = 0.5$. Parameters: $\text{CFL} = 0.9$, $\gamma = 2$, $c_V = 1$, $\varkappa = 0.8$.

Compound shock solution

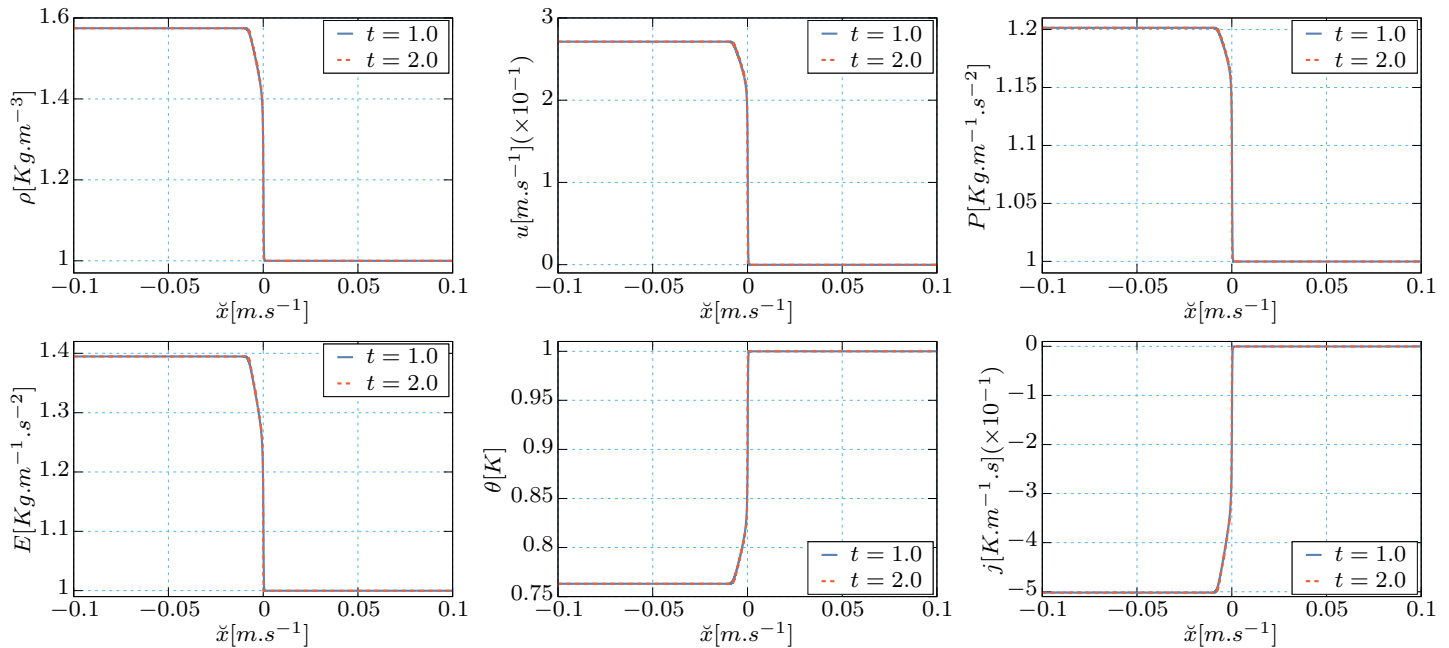


Figure 4: Compound shock plotted as a function of the self-similar coordinate $\check{x} = (x - D_{\star}t)/t$. CFL = 0.9, $\gamma = 2$, $c_V = 1$, $\varkappa = 1.3$.

Plan

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About Cahn-Hilliard equations

The Cahn-Hilliard equation is given by

$$\frac{\partial c}{\partial t} = \Delta (c^3 - c - \gamma \Delta c).$$

It admits the following Lyapunov functional $\left(\frac{dF}{dt} \leq 0 \right)$

$$F = \int_{\mathcal{D}} f(c, \nabla c) d\Omega, \quad f(c, \nabla c) = \frac{(c^2 - 1)^2}{4} + \frac{\gamma}{2} \|\nabla c\|^2$$

The C-H can also be written in conservative form as

$$\frac{\partial c}{\partial t} + \operatorname{div}(\mathbf{j}) = 0, \quad \mathbf{j} = \nabla \left(\frac{\partial f}{\partial c} - \operatorname{div} \left(\frac{\partial f}{\partial \nabla c} \right) \right)$$

Proposed action

Let us introduce the following action

$$a = \int_t \int_{\mathcal{D}} \mathcal{L} \, d\Omega \, dt, \quad \mathcal{L} = \frac{(c^2 - 1)^2}{4} + \frac{\gamma}{2} \|\nabla \varphi\|^2 + \frac{\lambda}{2} (c - \varphi)^2 - \frac{\beta}{2} \varphi_t^2$$

- φ is the new order parameter (distinguishes the phases).
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$$\frac{\partial c}{\partial t} = \operatorname{div} \left(\nabla \left(\frac{\partial \mathcal{L}}{\partial c} \right) \right), \quad \implies \quad \frac{\partial c}{\partial t} = \Delta (c^3 - c + \lambda (c - \varphi))$$

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$$\frac{\partial}{\partial t} \left(\frac{\partial \mathcal{L}}{\partial \varphi_t} \right) + \operatorname{div} \left(\frac{\partial \mathcal{L}}{\partial \nabla \varphi} \right) = \frac{\partial \mathcal{L}}{\partial \varphi} \quad \Longrightarrow \quad \beta \frac{\partial \varphi_t}{\partial t} - \operatorname{div} (\gamma \nabla \varphi) = \lambda(c - \varphi)$$

Cattaneo-type relaxation for first equation

We start from

$$\frac{\partial c}{\partial t} = \operatorname{div} (\nabla (c^3 - c + \lambda (c - \varphi)))$$

We apply classical relaxation ($\tau \ll 1$ is a characteristic time)

$$\begin{aligned} \frac{\partial c}{\partial t} + \operatorname{div} \left(\frac{1}{\tau} \mathbf{q} \right) &= 0, \\ \frac{\partial \mathbf{q}}{\partial t} + \nabla (c^3 - c + \lambda (c - \varphi)) &= -\frac{1}{\tau} \mathbf{q}, \end{aligned}$$

Order reduction for second equation

We start from

$$\beta \frac{\partial \varphi_t}{\partial t} - \operatorname{div}(\gamma \nabla \varphi) = \lambda(c - \varphi)$$

We denote

$$w = \beta \frac{\partial \varphi_t}{\partial t}, \quad \mathbf{p} = \nabla \varphi.$$

Thus obtaining the system

$$\begin{aligned} \frac{\partial w}{\partial t} - \operatorname{div}(\gamma \mathbf{p}) &= -\lambda(\varphi - c) \\ \frac{\partial \mathbf{p}}{\partial t} - \frac{1}{\beta} \nabla w &= 0 \\ \frac{\partial \varphi}{\partial t} &= \frac{1}{\beta} w \end{aligned}$$

First-order hyperbolic system for C-H equations

Regrouping all equations we get

$$\frac{\partial c}{\partial t} + \operatorname{div} \left(\frac{1}{\tau} \mathbf{q} \right) = 0$$

$$\frac{\partial \mathbf{q}}{\partial t} + \nabla (c^3 - c + \lambda(c - \varphi)) = -\frac{1}{\tau} \mathbf{q}$$

$$\frac{\partial w}{\partial t} - \operatorname{div} (\gamma \mathbf{p}) = -\lambda(\varphi - c)$$

$$\frac{\partial \mathbf{p}}{\partial t} - \frac{1}{\beta} \nabla w = 0$$

$$\frac{\partial \varphi}{\partial t} = \frac{1}{\beta} w$$

Energy decay

One can obtain an decay law for the total energy given by

$$\frac{\partial E}{\partial t} + \operatorname{div} \left(\frac{\partial E}{\partial c} \frac{\partial E}{\partial \mathbf{q}} - \frac{\partial E}{\partial w} \frac{\partial E}{\partial \mathbf{p}} \right) = - \left\| \frac{\partial E}{\partial \mathbf{q}} \right\|^2 \leq 0.$$

where the total energy E is

$$E(c, \varphi, w, \mathbf{p}, \mathbf{q}) = \frac{(c^2 - 1)^2}{4} + \frac{\gamma}{2} \|\mathbf{p}\|^2 + \frac{\lambda}{2} (c - \varphi)^2 + \frac{1}{2\beta} w^2 + \frac{1}{2\tau} \|\mathbf{q}\|^2$$

Hyperbolicity

In three dimensions of space, the eigenvalues are given by

$$\begin{aligned}\xi_{1-5} &= 0 \\ \xi_6 &= -\frac{\sqrt{3c^2 + \lambda - 1}}{\sqrt{\tau}} \\ \xi_7 &= \frac{\sqrt{3c^2 + \lambda - 1}}{\sqrt{\tau}} \\ \xi_8 &= -\frac{\sqrt{\gamma}}{\sqrt{\beta}} \\ \xi_9 &= \frac{\sqrt{\gamma}}{\sqrt{\beta}},\end{aligned}$$

for which a full basis of real eigenvectors exist.

Implicit fourth order FD on staggered grids for the original Cahn-Hilliard equations

$$\frac{\partial c}{\partial t} - \operatorname{div}(\chi \nabla c) + \gamma \Delta \Delta c = 0, \quad \chi = 3c^2 - 1$$

We propose the following scheme

$$c_{i,j}^{n+1} = c_{i,j}^n + \frac{\Delta t}{\Delta x} \left(\mathcal{F}_{i+\frac{1}{2},j}^{n+1} - \mathcal{F}_{i-\frac{1}{2},j}^{n+1} \right) + \frac{\Delta t}{\Delta y} \left(\mathcal{G}_{i,j+\frac{1}{2}}^{n+1} - \mathcal{G}_{i,j-\frac{1}{2}}^{n+1} \right) - \gamma \Delta \Delta_h c_{i,j}^{n+1}$$

$$\mathcal{F}_{i+\frac{1}{2},j}^{n+1} = \chi_{i+\frac{1}{2},j}^{n+1,r} (\nabla_x c)_{i+\frac{1}{2},j}^{n+1},$$

where

$$\begin{cases} \chi_{i+\frac{1}{2},j}^{n+1,r} \simeq \frac{1}{12} \left(7 \chi_{i,j}^{n+1,r} - \chi_{i-1,j}^{n+1,r} + 7 \chi_{i+1,j}^{n+1,r} - \chi_{i+2,j}^{n+1,r} \right) \\ (\nabla_x c)_{i+\frac{1}{2},j}^{n+1} \simeq -\frac{1}{12 \delta x} \left(15 c_{i-1,j}^{n+1} - 15 c_{i,j}^{n+1} + c_{i+1,j}^{n+1} - c_{i-2,j}^{n+1} \right) \end{cases}$$

(The same for \mathcal{G}^{n+1})

$\Delta\Delta_h c_{i,j}^{n+1}$ is a discretization of the bi-Laplacian operator in the cell-centers as follows

$$\begin{aligned} \Delta\Delta_h c_{i,j}^{n+1} = & -\frac{\Delta t}{\Delta x^4} \left(c_{i-2,j}^{n+1} - 4c_{i-1,j}^{n+1} + 6c_{i,j}^{n+1} - 4c_{i+1,j}^{n+1} + c_{i+2,j}^{n+1} \right) \\ & -\frac{\Delta t}{\Delta y^4} \left(c_{i,j-2}^{n+1} - 4c_{i,j-1}^{n+1} + 6c_{i,j}^{n+1} - 4c_{i,j+1}^{n+1} + c_{i,j+2}^{n+1} \right) \\ & -\frac{2\Delta t}{\Delta x^2 \Delta y^2} \left(c_{i-1,j-1}^{n+1} - 2c_{i,j-1}^{n+1} + c_{i+1,j-1}^{n+1} - 2c_{i-1,j}^{n+1} \right. \\ & \quad \left. + 4c_{i,j}^{n+1} - 2c_{i+1,j}^{n+1} + c_{i-1,j+1}^{n+1} - 2c_{i,j+1}^{n+1} + c_{i+1,j+1}^{n+1} \right) \end{aligned}$$

Comparison of hyperbolic and original CH: ODE solution

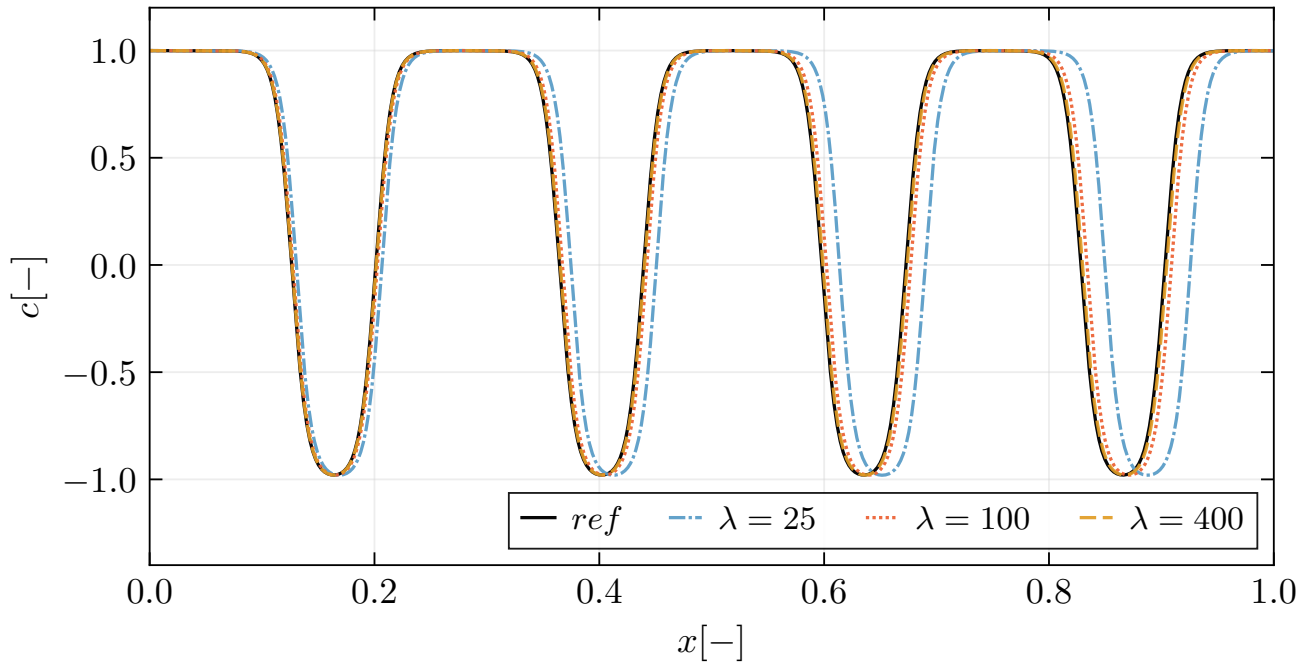


Figure 5: Comparison of a stationary solution of the hyperbolic model with the original counterpart for different values of λ .

Comparison of hyperbolic and original CH: 1D Ostwald Ripening

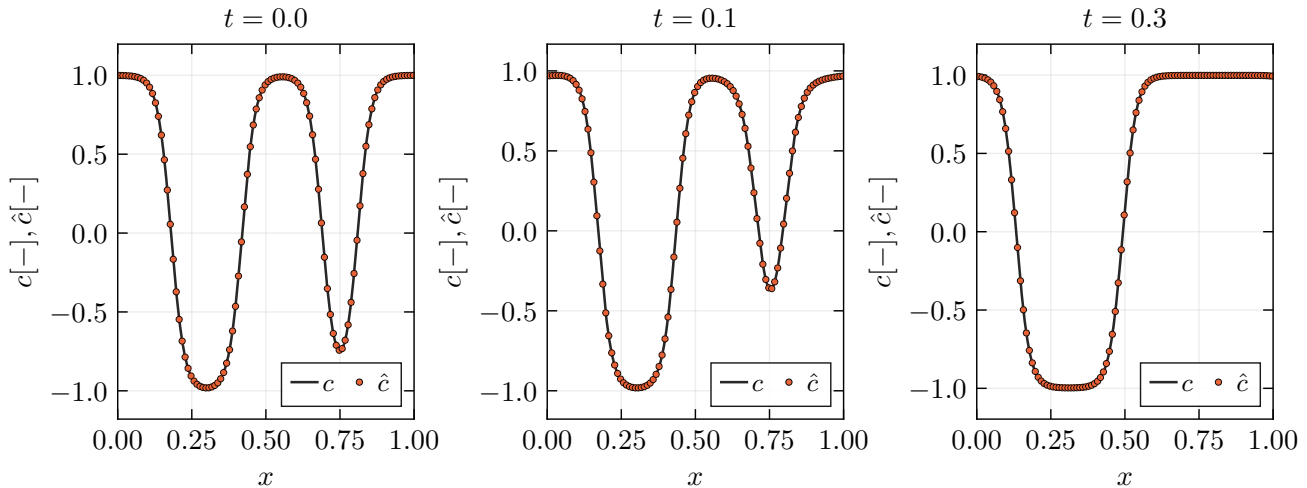
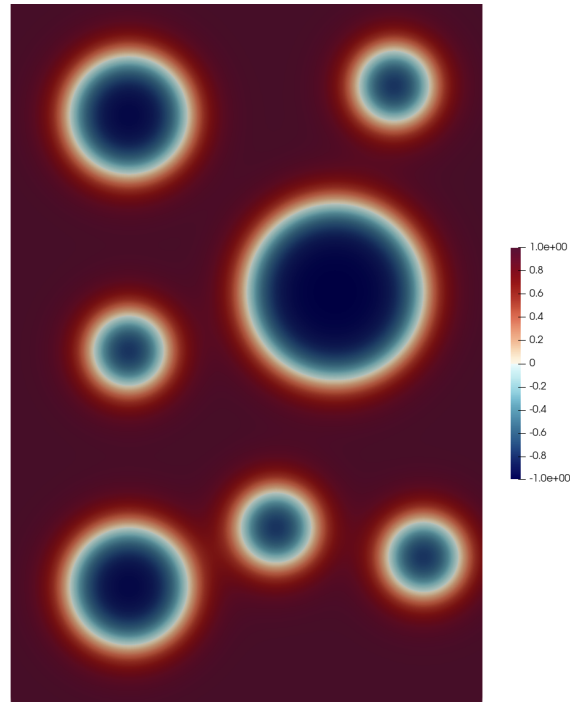


Figure 6: Comparison of Ostwald Ripening solution of the hyperbolic model with the original counterpart. Parameters are

Preliminary results for 2D Ostwald Ripening



Results obtained using explicit one-step fourth order ADER-DG.

Conclusion and Perspectives

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Perspectives

- Multi-D simulations for heat equation (accounting for curl-involutions, etc)
- Rigorous Justification of the relaxation limit
- Further optimization at the numerical level (semi-implicit discretization, etc)
- Preserving $-1 \leq c \leq 1$ numerically

Thank you for your attention !

[1] Dhaouadi, Firas, and Sergey Gavriluk. "An Eulerian hyperbolic model for heat transfer derived via Hamilton's principle: analytical and numerical study." Proceedings of the Royal Society A 480.2283 (2024): 20230440.

[2] Dhaouadi firas, Michael Dumbser and Sergey Gavriluk, "A first-order hyperbolic approximation to the Cahn-Hilliard equation". To be submitted. And references therein.

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