

# A hyperbolic augmented model for the NonLinear Schrödinger equation

Firas Dhaouadi  
Sergey Gavrilyuk  
Nicolas Favrie  
Jean-Paul Vila

Aix-Marseille Université - Université Toulouse III Paul Sabatier

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# about this PhD

- ED MITT : Mathématiques, Informatique et Télécommunications de Toulouse.
- University : Université Toulouse III Paul Sabatier.
- Officially started October 2017. Stayed until mid-January 2018 in IUSTI
- Spent two years at the maths department of INSA toulouse.
- Came back to IUSTI mid-January 2020.

# Classes of partial derivative equations

## Hyperbolic equations (e.g. $u_{tt} = cu_{xx}$ )

- Wave-like behaviour.
- perturbations propagate at finite speeds.
- Well-posed equations.

## parabolic equations (e.g. $u_t = \alpha u_{xx}$ )

- diffusive processes.
- perturbations propagate at infinite speeds.

## Elliptic equations (e.g. $u_{xx} = 0$ )

- mostly for steady states.
- Always smooth solutions.

# Classes of partial derivative equations

## Hyperbolic equations ✓

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## parabolic equations ✗

- diffusive processes.
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## Elliptic equations ✗

- mostly for steady states.
- Always smooth solutions.

# Some fluid dynamics models

- Euler Equations

$$\begin{cases} \partial_t \rho + \operatorname{div}(\rho \mathbf{u}) = 0 \\ \partial_t(\rho \mathbf{u}) + \operatorname{div}(\rho \mathbf{u} \otimes \mathbf{u}) + \nabla p(\rho) = 0 \end{cases}$$

- Navier-Stokes equations

$$\begin{cases} \partial_t \rho + \operatorname{div}(\rho \mathbf{u}) = 0 \\ \partial_t(\rho \mathbf{u}) + \operatorname{div}(\rho \mathbf{u} \otimes \mathbf{u}) + \nabla p(\rho) = \mu \nabla^2 \mathbf{u} \end{cases}$$

- Euler-Korteweg equations (constant capillarity)

$$\begin{cases} \partial_t \rho + \operatorname{div}(\rho \mathbf{u}) = 0 \\ \partial_t(\rho \mathbf{u}) + \operatorname{div}(\rho \mathbf{u} \otimes \mathbf{u}) + \nabla p(\rho) = \sigma \rho \nabla(\Delta \rho) \end{cases}$$

## Euler-Korteweg type systems

$$\begin{cases} \partial_t \rho + \operatorname{div}(\rho \mathbf{u}) = 0 \\ \partial_t(\rho \mathbf{u}) + \operatorname{div}(\rho \mathbf{u} \otimes \mathbf{u}) + \nabla p(\rho) = \rho \nabla (K(\rho) \Delta \rho + \frac{1}{2} K'(\rho) |\nabla \rho|^2) \end{cases}$$

$K(\rho) = \sigma$  : constant capillarity

$$\partial_t(\rho \mathbf{u}) + \operatorname{div}(\rho \mathbf{u} \otimes \mathbf{u}) + \nabla p(\rho) = \sigma \rho \nabla (\Delta \rho)$$

$K(\rho) = \frac{1}{4\rho}$  : Quantum capillarity / DNLS equation

$$\partial_t(\rho \mathbf{u}) + \operatorname{div}(\rho \mathbf{u} \otimes \mathbf{u} + \frac{1}{4\rho} \nabla \rho \otimes \nabla \rho) + \nabla \left( \frac{\rho^2}{2} - \frac{1}{4} \Delta \rho \right) = 0$$

- Definitely not hyperbolic and admits high order derivatives.
- **Ph.D Objective**  $\Rightarrow$  Make it first order hyperbolic !

# Outline

- 1 Defocusing Nonlinear Schrödinger equation
- 2 Augmented Lagrangian approach
- 3 Numerical results
- 4 Conclusions - Perspectives

# The Non-Linear Schrödinger equation

$$i\epsilon\psi_t + \frac{\epsilon^2}{2}\Delta\psi - f(|\psi|^2)\psi = 0 \quad ; \quad \epsilon = \frac{\hbar}{m}$$

- A wide range of applications: Nonlinear optics, quantum fluids, surface gravity waves
- Advantage : the equation is integrable. [Zakharov,Manakov 1974]
- Construction of analytical solutions is possible.
- In what follows and for simplicity we take  $\epsilon = 1$  and consider the cubic NLS equation  $f(|\psi|^2) = |\psi|^2$



# The defocusing NLS equation

$$i\psi_t + \frac{1}{2}\Delta\psi - |\psi|^2\psi = 0$$

## The Madelung transform

$$\psi(\mathbf{x}, t) = \sqrt{\rho(\mathbf{x}, t)}e^{i\theta(\mathbf{x}, t)} \quad \mathbf{u} = \nabla\theta$$

$$\begin{cases} \rho_t + \operatorname{div}(\rho\mathbf{u}) = 0 \\ (\rho\mathbf{u})_t + \operatorname{div}(\rho\mathbf{u} \otimes \mathbf{u} + \Pi) = 0 \end{cases}$$

$$\text{with : } \Pi = \left(\frac{\rho^2}{2} - \frac{1}{4}\Delta\rho\right)\mathbf{Id} + \frac{1}{4\rho}\nabla\rho \otimes \nabla\rho$$

# Lagrangian formulations

A Lagrangian :

$$\mathcal{L}(\rho, \mathbf{u}) = \int_{\Omega_t} \left( \frac{\rho |\mathbf{u}|^2}{2} - \rho e(\rho) \right) d\Omega_t$$

A Constraint :

$$\rho_t + \operatorname{div}(\rho \mathbf{u}) = \mathbf{0}$$

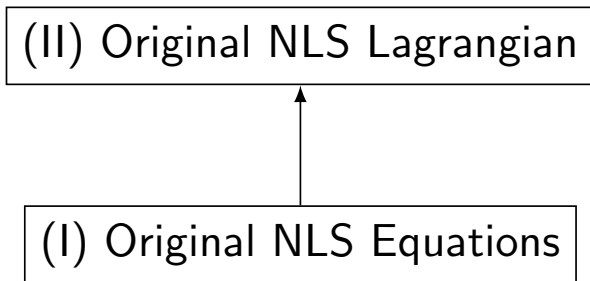
$\implies$  The corresponding Euler-Lagrange equation:

$$(\rho \mathbf{u})_t + \operatorname{div}(\rho \mathbf{u} \otimes \mathbf{u} + p(\rho)) = 0; \quad p(\rho) = \rho^2 e'(\rho)$$

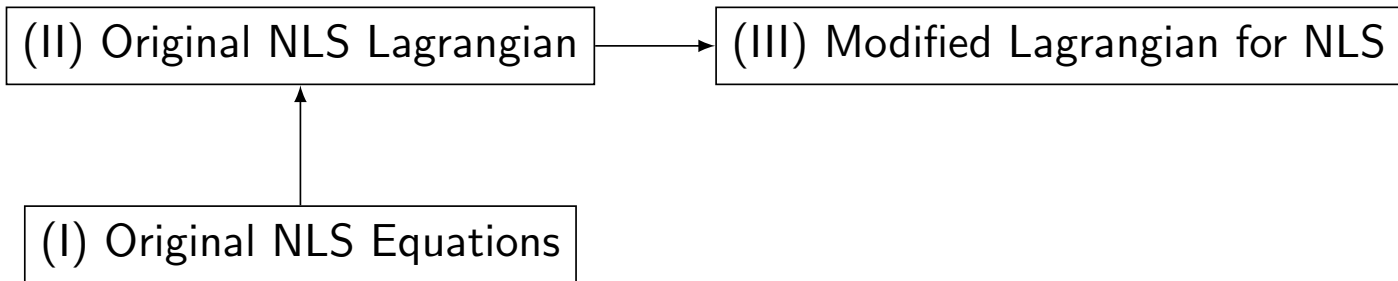
# Main Approach

(I) Original NLS Equations

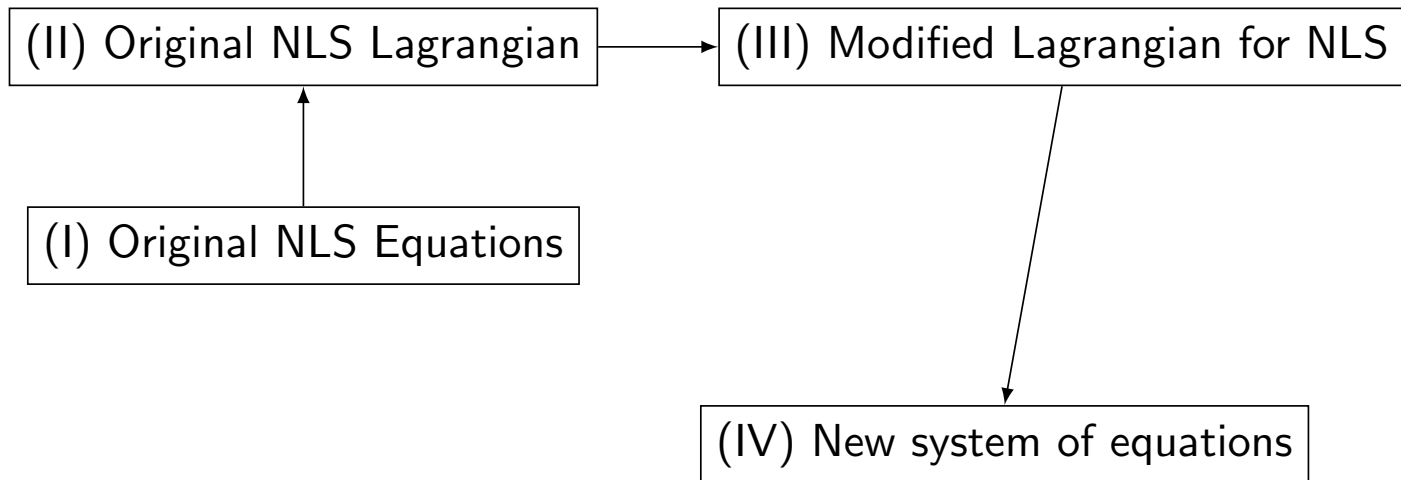
# Main Approach



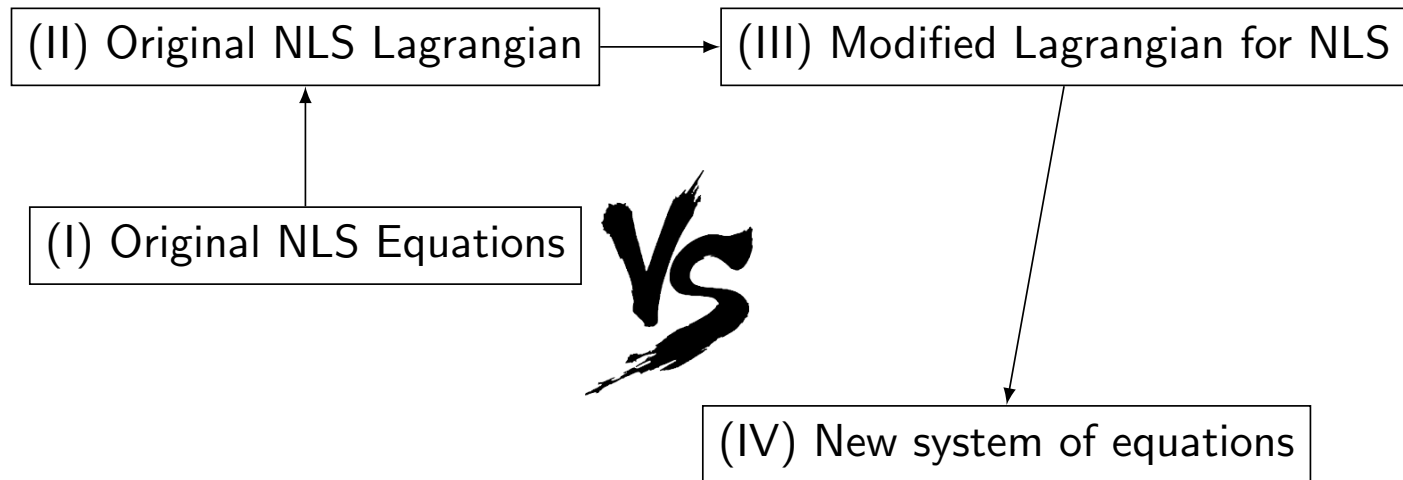
# Main Approach



# Main Approach



# Main Approach



# A Lagrangian for DNLS equation

$$\begin{cases} \rho_t + \operatorname{div}(\rho \mathbf{u}) = 0 \\ (\rho \mathbf{u})_t + \operatorname{div} \left( \rho \mathbf{u} \otimes \mathbf{u} + \left( \frac{\rho^2}{2} - \frac{1}{4} \Delta \rho \right) \mathbf{Id} + \frac{1}{4\rho} \nabla \rho \otimes \nabla \rho \right) = 0 \end{cases}$$

$$\mathcal{L}(\mathbf{u}, \rho, \nabla \rho) = \int_{\Omega_t} \left( \rho \frac{|\mathbf{u}|^2}{2} - \frac{\rho^2}{2} - \frac{1}{4\rho} \frac{|\nabla \rho|^2}{2} \right) d\Omega_t$$

**Energy conservation law:**

$$\frac{\partial E}{\partial t} + \operatorname{div}(E \mathbf{u} + \Pi \mathbf{u} - \frac{1}{4} \dot{\rho} \nabla \rho) = 0 \quad ; \quad \dot{\rho} = \rho_t + \mathbf{u} \cdot \nabla \rho$$

where

$$E = \rho \frac{|\mathbf{u}|^2}{2} + \frac{\rho^2}{2} + \frac{1}{4\rho} \frac{|\nabla \rho|^2}{2}$$



# Augmented Lagrangian approach

## The objective

Obtain a new Lagrangian whose Euler-Lagrange equations :

- are hyperbolic
- approximate Schrödinger's equation in a certain limit

## The idea

- Decouple  $\nabla\rho$  from  $\mathbf{u}$  and  $\rho$ , have it as an independent variable.

## Love affairs

Mass conservation :  $\rho_t + \operatorname{div}(\rho \mathbf{u}) = 0$

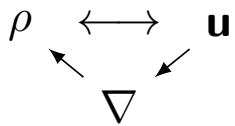
$\rho \longleftrightarrow \mathbf{u}$  (sweet love )

# Love affairs

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$\rho \longleftrightarrow \mathbf{u}$  (sweet love ❤️)      Love = Nice equations

$\rho \longleftrightarrow \mathbf{u}$       Nasty triangular = Ugly equations

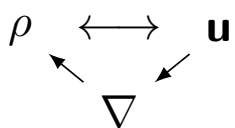


# Love affairs

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$\rho \longleftrightarrow \mathbf{u}$  (sweet love ❤️)      Love = Nice equations

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Solution: Call  $\eta$ , the twin brother of  $\rho$  to the rescue:

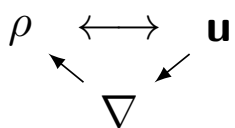
$\rho \longleftrightarrow \mathbf{u}$  ❤️       $\eta \longleftrightarrow \nabla \eta$  ❤️

# Love affairs

Mass conservation :  $\rho_t + \operatorname{div}(\rho \mathbf{u}) = 0$

$\rho \longleftrightarrow \mathbf{u}$  (sweet love ❤️)      Love = Nice equations

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Solution: Call  $\eta$ , the twin brother of  $\rho$  to the rescue:

$\rho \longleftrightarrow \mathbf{u}$  ❤️       $\eta \longleftrightarrow \nabla \eta$  ❤️

Twice the love = Even better equations!

# Augmented Lagrangian approach : Application to DNLS

DNLS Lagrangian :

$$\mathcal{L}(\mathbf{u}, \rho, \nabla \rho) = \int_{\Omega_t} \left( \rho \frac{|\mathbf{u}|^2}{2} - \frac{\rho^2}{2} - \frac{1}{4\rho} \frac{|\nabla \rho|^2}{2} \right) d\Omega_t$$

'Augmented' Lagrangian approach [Favrie, Gavriluk, 2017]

$$\tilde{\mathcal{L}}(\mathbf{u}, \rho, \eta, \nabla \eta)$$

$$\tilde{\mathcal{L}} = \int_{\Omega_t} \left( \rho \frac{|\mathbf{u}|^2}{2} - \frac{\rho^2}{2} - \frac{1}{4\rho} \frac{|\nabla \eta|^2}{2} - \frac{\lambda}{2\rho} (\eta - \rho)^2 \right) d\Omega_t$$

$$\frac{\lambda}{2} \rho \left( \frac{\eta}{\rho} - 1 \right)^2 : \text{Penalty}$$

# Augmented Lagrangian approach : Application to DNLS

DNLS Lagrangian :

$$\mathcal{L}(\mathbf{u}, \rho, \nabla \rho) = \int_{\Omega_t} \left( \rho \frac{|\mathbf{u}|^2}{2} - \frac{\rho^2}{2} - \frac{1}{4\rho} \frac{|\nabla \rho|^2}{2} \right) d\Omega_t$$

'Augmented' Lagrangian approach [Favrie, Gavriluk, 2017]

$$\tilde{\mathcal{L}}(\mathbf{u}, \rho, \eta, \nabla \eta, \dot{\eta})$$

$$\tilde{\mathcal{L}} = \int_{\Omega_t} \left( \rho \frac{|\mathbf{u}|^2}{2} - \frac{\rho^2}{2} - \frac{1}{4\rho} \frac{|\nabla \eta|^2}{2} - \frac{\lambda}{2\rho} (\eta - \rho)^2 + \frac{\beta\rho}{2} \dot{\eta}^2 \right) d\Omega_t$$

$$\frac{\lambda}{2\rho} \left( \frac{\eta}{\rho} - 1 \right)^2 : \text{Penalty}$$

$$\frac{\beta\rho}{2} \dot{\eta}^2 : \text{For regularity}$$

## Augmented system Euler-Lagrange equations

The Augmented Lagrangian :  $\mathbf{p} = \nabla\eta$  and  $w = \dot{\eta}$ .

$$\tilde{\mathcal{L}} = \int_{\Omega_t} \left( \rho \frac{|\mathbf{u}|^2}{2} + \frac{\beta\rho}{2} w^2 - \frac{\rho^2}{2} - \frac{1}{4\rho} \frac{|\mathbf{p}|^2}{2} - \frac{\lambda}{2} \rho \left( \frac{\eta}{\rho} - 1 \right)^2 \right) d\Omega_t$$

The constraint :

$$\rho_t + \operatorname{div}(\rho\mathbf{u}) = 0$$

$\implies$  We apply Hamilton's principle :

$$a = \int_{t_0}^{t_1} \tilde{\mathcal{L}} dt \implies \delta a = 0$$



# Types of variations

Two types of variations will be considered :

$$\tilde{\mathcal{L}}(\underbrace{\mathbf{u}, \rho, \dot{\eta}, \eta, \nabla \eta}_{II}) \quad \dot{\eta} = \eta_t + \mathbf{u} \cdot \nabla \eta$$

- Type I : Virtual displacement of the continuum:

$$\hat{\delta} \rho = -\operatorname{div}(\rho \delta \mathbf{x}) \quad \hat{\delta} \mathbf{u} = \delta \dot{\mathbf{x}} - \nabla \mathbf{u} \cdot \delta \mathbf{x} \quad \delta \dot{\eta} = \hat{\delta} \mathbf{u} \cdot \nabla \eta$$

- Type II : Variations with respect to  $\eta$

$$\delta \nabla \eta = \nabla \delta \eta \quad \delta \dot{\eta} = (\delta \eta)_t + \mathbf{u} \cdot \nabla \delta \eta$$

# Augmented system Euler-Lagrange Equations

- Type I : Virtual displacement of the continuum:

$$\boxed{(\rho \mathbf{u})_t + \operatorname{div} (\rho \mathbf{u} \otimes \mathbf{u} + \mathbf{P}) = 0}$$

with : 
$$\mathbf{P} = \left( \frac{\rho^2}{2} - \frac{1}{4\rho} |\mathbf{p}|^2 + \eta \lambda \left( 1 - \frac{\eta}{\rho} \right) \right) \mathbf{Id} + \frac{1}{4\rho} \mathbf{p} \otimes \mathbf{p}$$

- Type II : Variations with respect to  $\eta$ :

$$\boxed{(\rho w)_t + \operatorname{div} \left( \rho w \mathbf{u} - \frac{1}{4\rho\beta} \mathbf{p} \right) = \frac{\lambda}{\beta} \left( 1 - \frac{\eta}{\rho} \right)}$$

# Closure of the system

## 1. Definition of $w = \dot{\eta}$

$$w = \dot{\eta} = \eta_t + \mathbf{u} \cdot \nabla \eta \quad \Longrightarrow \quad \boxed{(\rho\eta)_t + \operatorname{div}(\rho\eta\mathbf{u}) = \rho w}$$

## 2. Evolution of $\mathbf{p} = \nabla \eta$

$$\begin{aligned} \nabla w &= \nabla(\eta_t + \mathbf{u} \cdot \nabla \eta) \\ &= (\nabla \eta)_t + \nabla(\mathbf{u} \cdot \nabla \eta) \\ \Longrightarrow & \quad (\nabla \eta)_t + \nabla(\mathbf{u} \cdot \nabla \eta - w) = 0 \\ \Longrightarrow & \quad \boxed{\mathbf{p}_t + \operatorname{div}((\mathbf{p} \cdot \mathbf{u} - w)\mathbf{Id}) = 0} \end{aligned}$$

## 2'. Initial condition for $\mathbf{p}$ : $\mathbf{p}_{t=0} = (\nabla \eta)_{t=0}$

# The full Augmented system

$$\left\{ \begin{array}{l} \rho_t + \operatorname{div}(\rho \mathbf{u}) = 0 \\ (\rho \mathbf{u})_t + \operatorname{div}(\rho \mathbf{u} \otimes \mathbf{u} + \mathbf{P}) = 0 \\ (\rho \eta)_t + \operatorname{div}(\rho \eta \mathbf{u}) = \rho w \\ (\rho w)_t + \operatorname{div}\left(\rho w \mathbf{u} - \frac{1}{4\rho\beta} \mathbf{p}\right) = \frac{\lambda}{\beta} \left(1 - \frac{\eta}{\rho}\right) \\ \mathbf{p}_t + \operatorname{div}((\mathbf{p} \cdot \mathbf{u} - w) \mathbf{Id}) = 0; \quad \operatorname{curl}(\mathbf{p}) = 0 \end{array} \right.$$

$$\mathbf{P} = \left( \frac{\rho^2}{2} - \frac{1}{4\rho} |\mathbf{p}|^2 + \eta\lambda \left(1 - \frac{\eta}{\rho}\right) \right) \mathbf{Id} + \frac{1}{4\rho} \mathbf{p} \otimes \mathbf{p}$$

- Closed system (5 independent equations for 5 variables.
- What about hyperbolicity ? it is unconditionally hyperbolic.
- Values of  $\lambda$  and  $\beta$  ?

# Numerical scheme : Hyperbolic step

**1-d system of equations to solve :**

$$\frac{\partial \mathbf{U}}{\partial t} + \frac{\partial \mathbf{F}}{\partial x} = \mathbf{S}(\mathbf{U})$$

**Hyperbolic part:**

- ① Godunov scheme:  $\mathbf{U}_i^{n+1} = \mathbf{U}_i^n - \frac{\Delta t}{\Delta x} \left( \mathbf{F}_{i+\frac{1}{2}}^* - \mathbf{F}_{i-\frac{1}{2}}^* \right)$
- ② Riemann Solver: Rusanov.

$$\mathbf{F}_{i+\frac{1}{2}} = \frac{1}{2} \left( \mathbf{F}(\mathbf{U}_{i+1}^n) - \mathbf{F}(\mathbf{U}_i^n) \right) - \frac{1}{2} \kappa_{i+\frac{1}{2}}^n \left( \mathbf{U}_{i+1}^n - \mathbf{U}_i^n \right)$$

where  $\kappa_{i+\frac{1}{2}}^n$  is obtained by using the Davis approximation :

$$\kappa_{i+\frac{1}{2}}^n = \max_j \left( |c_j(\mathbf{U}_i^n)|, |c_j(\mathbf{U}_{i+1}^n)| \right),$$

where  $c_j$  are the eigenvalues of the Augmented system.

## Numerical scheme : ODE step

Reduced to a second order ODE with constant coefficients which can be solved exactly in our case.

$$\left\{ \begin{array}{l} \frac{d\rho}{dt} = 0; \quad \frac{d\rho u}{dt} = 0; \quad \frac{dp}{dt} = 0 \quad \frac{d\rho\eta}{dt} = \rho w \quad \frac{d\rho w}{dt} = \frac{\lambda}{\beta} \left( 1 - \frac{\eta}{\rho} \right) \end{array} \right.$$

Therefore, the exact solution is given by :

$$\left\{ \begin{array}{l} \rho^{n+1} = \bar{\rho}^n \quad u^{n+1} = \bar{u}^n \quad p^{n+1} = \bar{p}^n \\ \eta^{n+1} = \bar{\rho}^n + (\bar{\eta}^n - \bar{\rho}^n) \cos(\Omega\Delta t) + \frac{\bar{w}^n}{\Omega} \sin(\Omega\Delta t) \\ w^{n+1} = \Omega(\bar{\rho}^n - \bar{\eta}^n) \sin(\Omega\Delta t) + \bar{w}^n \cos(\Omega\Delta t) \end{array} \right.$$

where  $\Omega = \frac{\lambda}{\beta\rho^2}$ .

# A brief introduction to DSWs

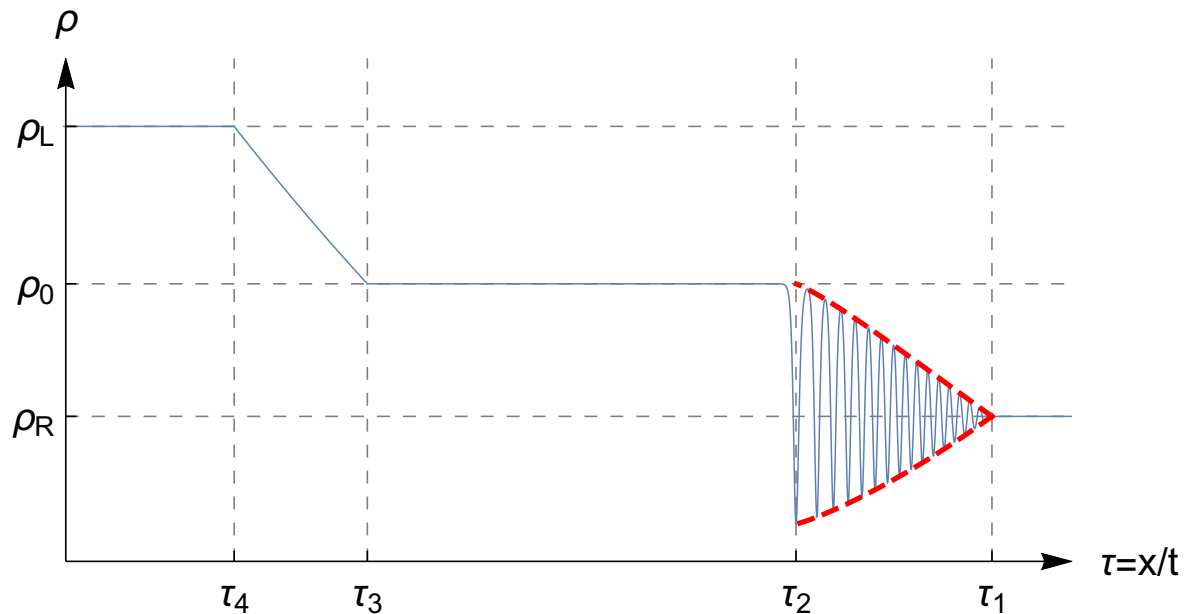


Figure 1: Asymptotic profile of the solution to NLS equation (continuous line) for the Riemann problem  $\rho_L = 2$ ,  $\rho_R = 1$ ,  $u_L = u_R = 0$ . Oscillations shown at  $t=70$

# DSW Numerical results : $\rho$

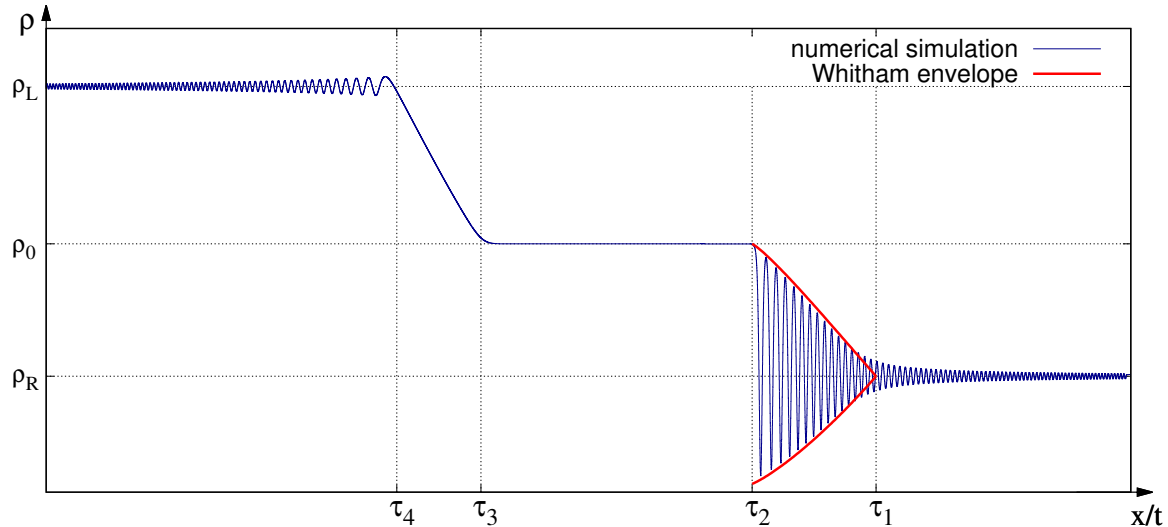


Figure 2: Comparison of the numerical result  $\rho(x, t) = f(x/t)$  (blue line) with the asymptotic profile of the oscillations from Whitham's theory of modulations.  $t=70$



# DSW Numerical results : $u$

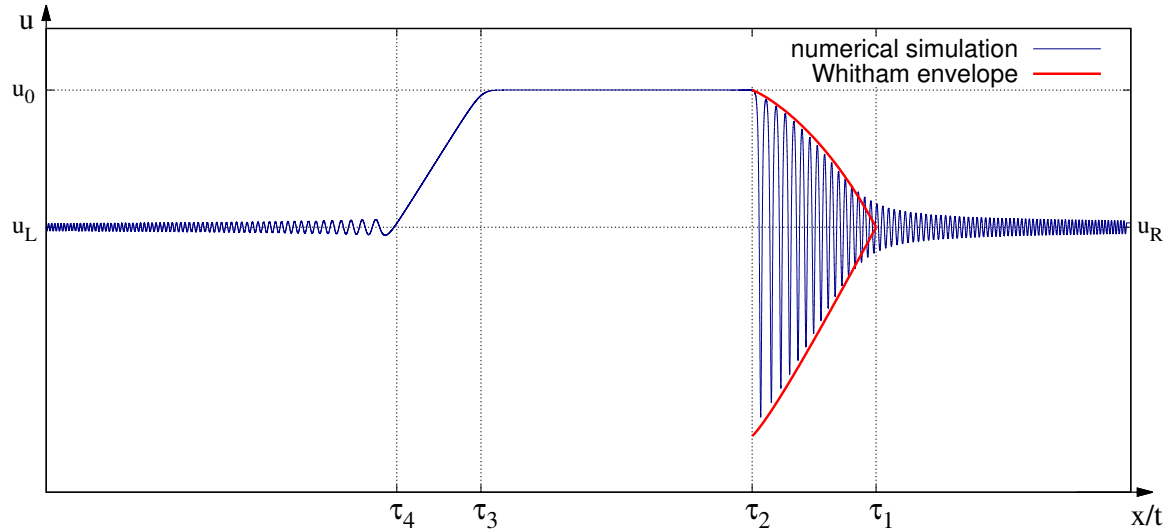


Figure 3: Comparison of the numerical result  $u(x, t) = f(x/t)$  (blue line) with the asymptotic profile of the oscillations from Whitham's theory of modulations.  $t=70$

# Conclusions - perspectives

## Conclusions :

- An approximate first order hyperbolic model for the defocusing nonlinear Schrödinger equation based on an augmented Lagrangian method.
- Tests were made for a non stationary solution (DSWs).

## Perspectives (already done) :

- Obtained results for thin film flows with surface tension (another system of the Euler-Korteweg type)
- A more suitable numerical scheme (2nd order IMEX)

## Perspectives (yet to be done, actually never ...) :

- Extension to the multidimensional case.
- Proper development of the boundary conditions.
- Further optimization of the numerical resolution.

Thank you for your attention :) !

## F.A.Q :

- Obtaining the red envelope for the oscillatory wave train.
- What happens if you take a real discontinuity as initial condition ?
- How does the penalty method work.
- How we obtain both Euler Lagrange equations
- what boundary conditions do we use ?
- Do we have hyperbolicity in the multidimensional case ?
- Are the schemes we use Asymptotic Preserving ?
- Ensuring the curl-free constraint on  $\mathbf{p}$  in multi-D.

# One-Dimensional case : Hyperbolicity

In order to study the hyperbolicity of this system, we write it in quasi-linear form :

$$\frac{\partial \mathbf{U}}{\partial t} + \mathbf{A}(\mathbf{U}) \frac{\partial \mathbf{U}}{\partial x} = \mathbf{q}$$

where:

$$\mathbf{U} = \left( \rho, u, w, p, \eta \right)^T \quad \mathbf{q} = \left( 0, 0, \frac{1\lambda}{\beta\rho} \left( 1 - \frac{\eta}{\rho} \right), 0, w \right)^T$$

$$\mathbf{A}(\mathbf{U}) = \begin{pmatrix} u & \rho & 0 & 0 & 0 \\ 1 + \frac{\lambda\eta^2}{\rho^3} & u & 0 & 0 & \frac{\lambda}{\rho} \left( 1 - \frac{2\eta}{\rho} \right) \\ \frac{p}{4\beta\rho^3} & 0 & u & -\frac{1}{4\beta\rho^2} & 0 \\ 0 & p & -1 & u & 0 \\ 0 & 0 & 0 & 0 & u \end{pmatrix}$$

## One-Dimensional case : Hyperbolicity

The eigenvalues  $c$  of the matrix  $\mathbf{A}$  are :

$$c = u, (c - u)_{\pm}^2 = \frac{\left(\frac{1}{4\beta\rho^2} + \rho + \frac{\lambda\eta^2}{\rho^2}\right) \pm \sqrt{\left(-\frac{1}{4\beta\rho^2} + \rho + \frac{\lambda\eta^2}{\rho^2}\right)^2}}{2}.$$

The right-hand side is always positive. However, the roots can be multiple if

$$\frac{1}{4\beta\rho^2} = \rho + \frac{\lambda\eta^2}{\rho^2}.$$

In the case of multiple roots : We still get five linear independent eigenvectors.  $\implies$  the system is always hyperbolic

## Values of $\lambda$ and $\beta$

- Values have to be assigned : a criterion is needed.
- We can base this choice, for example, on the dispersion relation.

### Original DNLS dispersion relation

$$c_p^2 = \rho_0 + \frac{k^2}{4}$$

### Augmented DNLS dispersion relation

$$(c_p)^2 = \frac{\frac{1}{4\beta\rho_0^2} + \rho_0 + \lambda + \frac{\lambda}{\beta\rho_0^2 k^2} - \sqrt{\left(\frac{1}{4\beta\rho_0^2} + \rho_0 + \lambda + \frac{\lambda}{\beta\rho_0^2 k^2}\right)^2 - 4\left(\frac{\lambda}{\beta\rho_0 k^2} + \frac{\rho_0 + \lambda}{4\beta\rho_0^2}\right)}}{2}$$

## Example estimation

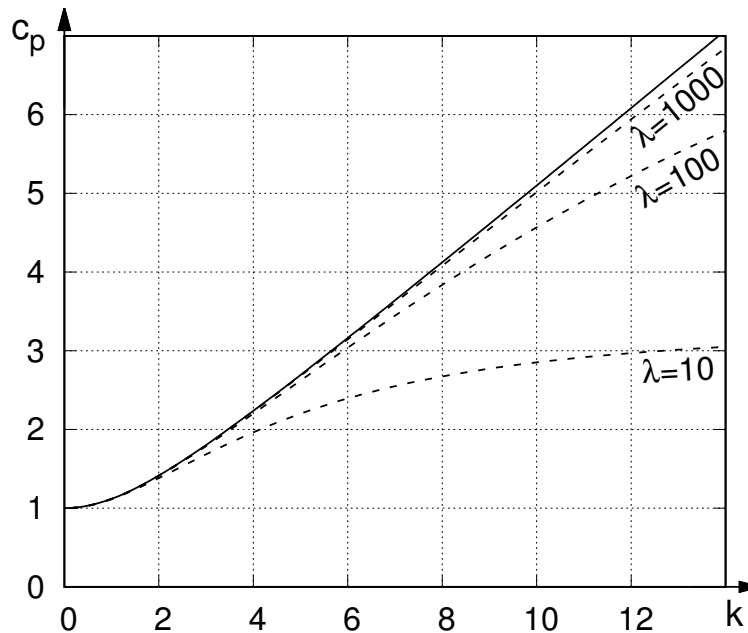


Figure 4: The dispersion relation  $c_p = f(k)$  for the original model (continuous line) and the dispersion relation for the Augmented model (dashed lines) for different values of  $\lambda$  and for  $\beta = 10^{-4}$

# vanishing oscillations at the left constant state

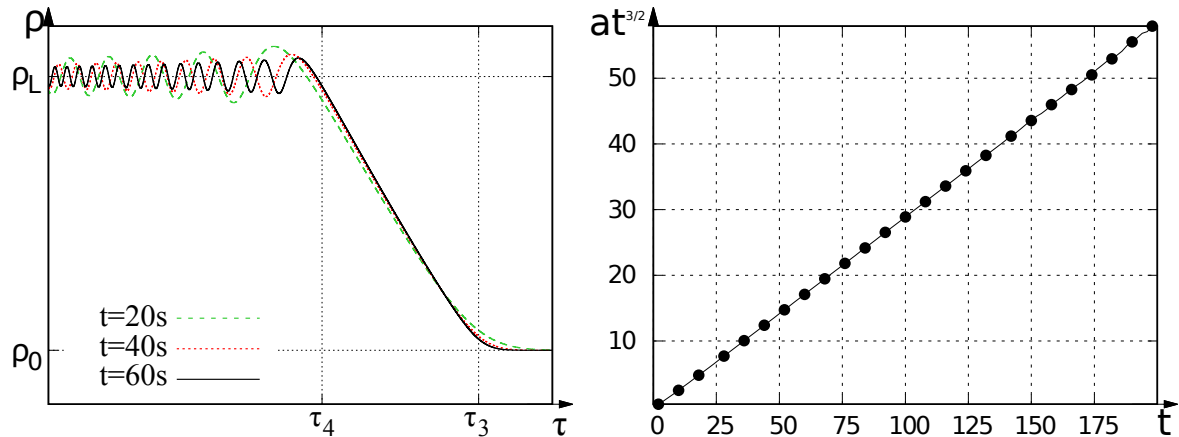


Figure 5: Vanishing oscillations at the vicinity of  $\tau = \tau_4$ . amplitude decreases as  $\propto t^{-1/2}$ .